|  |  |
| --- | --- |
| Team Meeting | 2/10/20203:30pmJD Hall room 2016 |

|  |  |  |  |
| --- | --- | --- | --- |
| Meeting called by: | Class Scheduled | Type of meeting: | Biweekly Sprint Meeting |
| Facilitator: | Professor Douchette | Note taker: | Daniel Cardenas |
| Timekeeper: | Daniel Cardenas |  |  |

|  |  |
| --- | --- |
| Attendees: | Brandon, Gage, Gigi, Daniel |
| Please read: | n/a |
| Please bring: | n/a |

# Minutes

|  |  |  |  |
| --- | --- | --- | --- |
| Agenda item: | Update on individual progress and formulate plans until next sprint | Presenter: | n/a |

#### Discussion:

To get started right away, just tap any placeholder text (such as this) and start typing to replace it with your own.

#### Conclusions:

Enter conclusions here.

| Action items | Person responsible | Deadline |
| --- | --- | --- |
| * Write out code for implementation of python A-star algorithm; translate and run to test. | Daniel | 2/19/20 |
| * Learn how to write into a forbidden directory (in python) in linux | Brandon | 2/19/20 |
| * Writing waypoints to the waypoint file then get it to call it and run it | Brandon and Gage | 2/19/20 |

# Other Information

#### Special notes:

Translator Process:

- translator runs

- translator write to yaml file

- sends to ROS

- run package once; writes the file; (translator is subscribing to an lcm; running the scripts performs this)

\*\*this is listening to initial waypoints; also have subscriber reading info from ROV and passing it back, essentially a publisher pushing back;

\*\* would like to have one package for everything at some point, instead of multiple terminals needing to be open

- packages in lib and packages in share

- share is for launch files such as yaml files